

I/O and I/S/O representation of SISO linear systems	
I/O	I/S/O
variables: (u, y) $q\left(\frac{d}{dt}\right)y(t) = p\left(\frac{d}{dt}\right)u(t), n = \deg q \geq \deg p$ $u(t), y(t) \in \mathbb{R}$	variables: (u, x, y) $\frac{d}{dt}x(t) = Ax(t) + Bu(t), y(t) = Cx(t) + Du(t)$ $x(t) \in \mathbb{R}^n, \left(\begin{array}{c c} A & B \\ \hline C & D \end{array}\right) \in \mathbb{R}^{(n+1) \times (n+1)}$
Impulse response	
$q\left(\frac{d}{dt}\right)h(t) = p\left(\frac{d}{dt}\right)\delta(t)$ $H(s) = \mathcal{L}(h(t)) = \frac{p(s)}{q(s)}$	$h(t) = D\delta(t) + Ce^{At}B, t \geq 0$ $H(s) = D + C(sI - A)^{-1}B$
Poles - characteristic roots - eigenfrequencies	
$\lambda_i, q(\lambda_i) = 0, i = 1, \dots, n$	$\det(\lambda_i I - A) = 0$
Zeros	
$H(z_i) = 0 \Leftrightarrow p(z_i) = 0, i = 1, \dots, n$	$\det\left(\begin{array}{cc} z_i I - A & -B \\ -C & -D \end{array}\right) = 0$
Matrix exponential	
	$e^{At} = \sum_{k=0}^{\infty} \frac{t^k}{k!} A^k \Rightarrow \frac{d}{dt}e^{At} = Ae^{At} = e^{At}A$ $\mathcal{L}(e^{At}) = (sI - A)^{-1}$
BIBO stability	
$y = h * u$, requirement $\forall u \ni \ u\ _{\infty} < \infty \Rightarrow \ y\ _{\infty} < \infty$ $\Leftrightarrow \ h\ _1 = \int_0^{\infty} h(t) dt < \infty$ $\Leftrightarrow \operatorname{Re}(\lambda_i) < 0 \Leftrightarrow \text{poles} \in \text{LHP}$	
Solution in the time domain	
$y(t) = y_{zi}(t) + y_{zs}(t)$ $y(t) = \sum_{i=1}^n c_i e^{\lambda_i t} + \int_{0^-}^t h(t - \tau)u(\tau) d\tau$	$x(t) = x_{zi}(t) + x_{zs}(t)$ $x(t) = e^{At}x(0^-) + \int_{0^-}^t e^{A(t-\tau)}Bu(\tau) d\tau$ $y(t) = Ce^{At}x(0^-) + \int_{0^-}^t \underbrace{(D\delta(t - \tau) + Ce^{A(t-\tau)}B)}_{h(\cdot)} u(\tau) d\tau$ $y(t) = Ce^{At}x(0^-) + \int_{0^-}^t h(t - \tau)u(\tau) dt$
\mathcal{L} : Solution in the frequency domain	
$Y(s) = \frac{r(s)}{q(s)} + H(s)U(s)$	$X(s) = (sI - A)^{-1}x(0^-) + (sI - A)^{-1}BU(s)$ $Y(s) = C(sI - A)^{-1}x(0^-) + \underbrace{(D + C(sI - A)^{-1}B)}_{H(s)}U(s)$

Definition of state from I/O description. Let $H(s) = D + \frac{\bar{p}(s)}{q(s)}$, $\deg \bar{p} < \deg q$. Define w so that $q\left(\frac{d}{dt}\right)w(t) = u(t), y(t) = \bar{p}\left(\frac{d}{dt}\right)w + Du(t) \Rightarrow x^T = \begin{pmatrix} w & w^{(1)} & \dots & w^{(n-1)} \end{pmatrix} \in \mathbb{R}^n, n$: degree of $q(s)$.

Various responses.

Zero-input or *free* response: response due to initial conditions alone.

Zero-state or *forced* response: response due to input (forcing function) alone (zero initial conditions).

Homogeneous solution: general form of free-response (arbitrary initial conditions).

Particular solution: forced response.

Steady-state response: response obtained for large values of time $T \rightarrow \infty$.

Transient response: full response minus steady state response.